The following tables provide the results of all mixed ANOVAs conducted for sense of embodiment, self-identification, eeriness, and both body weight estimation tasks.

Table 1: Results of the calculated 2×2 mixed ANOVAs of the main and interaction effects of motor control and self-similarity factors for sense of embodiment, self-identification, and eerieness. Statistical significance in dicators: *p < 0.05; *p < 0.01; *p < 0.001.

| | Main Effect Motor Control | Main Effect Self-Similarity | Interaction Effect |
|--------------------------------|--|--|---------------------------------------|
| Sense of Embodiment | | | |
| VEQ Virtual Body Ownership | F(1,57) = 2.982, p = .090 | $F(1,57) = 33.767, p < .001^{\ddagger}$ | F(1,57) = 0.031, p = .860 |
| VEQ Agency | $F(1,57) = 153.634, p < .001^{\ddagger}$ | $F(1,57) = 13.041, p < .001^{\ddagger}$ | $F(1,57) = 7.368, p = .009^{\dagger}$ |
| VEQ+ Self-Location | F(1,57) = 2.551, p = .116 | $F(1,57) = 28.264, p < .001^{\ddagger}$ | F(1,57) = 0.465, p = .498 |
| Self-Identification | | | |
| VEQ+ Self-Attribution | F(1,57) = 3.558, p = .064 | $F(1,57) = 44.836, p < .001^{\ddagger}$ | F(1,57) = 0.202, p = .655 |
| VEQ+ Perceived Self-Similarity | F(1,57) = 0.231, p = .633 | $F(1,57) = 110.835, p < .001^{\ddagger}$ | F(1,57) = 0.986, p = .325 |
| Eerieness | | | |
| UVI Eerieness | F(1,57) = 0.265, p = .609 | F(1,57) = 1.980, p = .165 | F(1,57) = 1.532, p = .221 |

Table 2: Results of the calculated $2 \times 2 \times 2$ mixed ANOVAs or ANOVA-type statistics (marked with np) of the main and interaction effects of the factors motor control, self-similarity, and gender for both body weight perception tasks. Statistical significance indicators: *p < 0.05; †p < 0.01; *p < 0.01;

| | Passive Estimation Task (PET) | | Active Modification Task (AMT) | |
|--|---|---|--|-------------------------------|
| | Misestimation M in % | Misestimation A in % | Current Body Weight in % | Ideal Body Weight in % |
| Main Effect | | | | |
| Motor Control | F(1,55) = 0.534, p = .468 | F(1,55) = 0.569, p = .454 | F(1,55) = 0.083, p = .775 | F(1,55) = 0.230, p = .633 |
| Self-Similarity | $F(1,55) = 13.132, p < .001^{\ddagger}$ | $F(1,55) = 15.691, p < .001^{\ddagger}$ | $F(1,55) = 8.223, p = .006^{\dagger}$ | F(1,55) = 1.782, p = .187 |
| Gender | $F(1,55) = 5.653, p = .021^*$ | F(1,55) = 2.143, p = .149 | $F(1,55) = 11.185, p = .001^{\dagger}$ | F(1,55) = 2.920, p = .093 |
| Interaction Effect | | | | |
| Motor Control x Self-Similarity | F(1,55) = 0.797, p = .376 | F(1,55) = 0.157, p = .693 | F(1,55) = 0.131, p = .719 | $F(1,55) = 4.212, p = .045^*$ |
| Motor Control x Gender | F(1,55) = 0.001, p = .974 | F(1,55) = 0.223, p = .639 | F(1,55) = 0.112, p = .728 | F(1,55) = 0.120, p = .730 |
| Self-Similarity x Gender | $F(1) = 1.778^{np}, p = .182$ | $F(1,55) = 10.573, p = .002^*$ | F(1,55) = 0.255, p = .615 | F(1,55) = 0.197, p = .659 |
| Motor Control x Self-Similarity x Gender | F(1,55) = 0.043, p = .837 | F(1,55) = 0.040, p = .843 | F(1,55) = 0.324, p = .571 | F(1,55) = 0.020, p = .889 |